Compressive Symmetry

Matteo Fischetti, University of Padova Leo Liberti, LIX, Ecole Polytechnique, France



Motivation





Fig. 1. Pattern whose symmetry group is (5, 4, 7) (with reaffolding). Two adjacent triangles (one white and one block) form a fundamental region.

scientists

all like symmetry

Nature,

people,

Why not us?

Symmetry for dummies

• Consider a generic optimization problem of the form

 $v(P) := \min\{f(x) : x \in F(P)\}$

where $F(P) \subseteq \mathcal{R}^n$ and $f : \mathcal{R}^n \to \mathcal{R}$

• A symmetry permutation is an index permutation

$$\pi: \{1, \cdots, n\} \to \{1, \cdots, n\}$$

such that

$$x \in F(P) \Rightarrow x' \in F(P)$$
 and $f(x') = f(x)$

where $x'_{\pi(j)} := x_j$ for all $j \in \{1, \cdots, n\}$



Symmetry permutation (illustration)



permutation = node covering by disjoint directed cycles

Symmetry group

- **Symmetry group G**: finite collection of symmetry permutations closed under composition and inversion
- **Generators** of G: set of symmetry permutations whose composition (and inversion) yields G
- **Orbits of G**: indices *i* and *j* belong to a same orbit iff there exist π in G such that $\pi(i) = j$



Generators and orbits (example)



orbits = strongly-connected components of generator graph

Nice, but... how to compute them?

- In some cases, a suitable (sub) group is known a priori
- Otherwise, it can be computed starting from the available mathematical formulation of the problem ...

... hoping the user was not so clever to use sophisticated tricks (e.g., lifted cuts) that hide symmetry

- Reasonably fast in practice through sw such as saucy, nauty, etc.
- So, let's assume a suitable symmetry group G has been computed with "reasonable" overhead

Symmetry and convex optimization

- Assume both *F*(*P*) and *f* are convex
- Fact (Parrilo, 2003): an optimal solution \overline{x} exists such that

 $\overline{x}_j = \text{const.}$ within each orbit O_h

Argument:

- if f is strictly convex, a unique optimal solution x^* exists, so each π in G must leave x^* unchanged \rightarrow equal value within each orbit
- if not, just consider a second-level strictly convex function p to break ties...

Claim: there exists an optimal solution \overline{x} such that

 $\overline{x}_i = \text{const.}$ within each orbit O_h

Indeed, let x^* be an optimal solution with minimum

$$\rho(x^*) := \sum_{j=1}^n (x_j^*)^2$$

Assume, by contradiction, that there exist $i, j \in O_h$ such that $x_i^* \neq x_j^*$

- As i, j belong a same orbit, there exists π in G such that $\pi(i) = j$.
- Let y^* be an optimal solution obtained from x^* by applying π , where $x^* \neq y^*$ and $\rho(y^*) = \rho(x^*)$.
- By convexity, the point $z^* := (x^* + y^*)/2$ is an optimal solution as well, while $\rho(z^*) < (\rho(x^*) + \rho(y^*))/2 = \rho(x^*)$ because ρ is strictly convex.

$$\begin{array}{ll} i \ j \\ x^* = (2, 1, 1, 1)(3, 4) & (5, 5)(1, 1, 1, 1) \\ y^* = (1, 2, 1, 1)(4, 3) & (5, 5)(1, 1, 1, 1) \\ | \leftarrow O_1 \rightarrow | & | \leftarrow O_2 \rightarrow | \end{array}$$

Symmetry helps in the convex case

- Because of the above, the only unknowns in the convex case are the k values of x̄ inside O1,...,Ok
- Exact reformulation
 - 1. introduce additional variables

$$z_h = \sum_{j \in O_h} x_j, \quad h = 1, \cdots, k$$



2. project the formulation on the z-space, by just replacing

 $x_j \to z_h / |O_h|$ for all $j \in O_h$, $h = 1, \cdots, k$

3. solve the projected model on the z-space

Symmetry hurts in the nonconvex case

- Unfortunately, the average point \overline{x} can be infeasible/nonoptimal in the nonconvex case \rightarrow reformulation does not work!
- Even worse: in the discrete case, **enumeration** is tricked by symmetry (symmetric subtrees can be visited again and again...)
- Possible remedies:
- a. Break symmetry somehow
 → a potentially useful property is not fully exploited!



b. Modify branching rules (isomorphism pruning, orbital branching) to take advantage of symmetry → a powerful idea!

Symmetry in convex MI(N)LP

• Consider the convex Integer (N)LP

 $(P) \quad v(P) := \min\{f(x) : x \in F(P), x \text{ integer}\}$ where $F(P) \subseteq \mathcal{R}^n$ and $f : \mathcal{R}^n \to \mathcal{R}$ are both convex.

(mixed-integer case very similar, with integer/continuous orbits)

- Feasible set is **nonconvex** \rightarrow reformulation on the z-space is **not** exact
- Can we exploit the symmetry group anyway?
- E.g., within an enumerative method, at each node compute the symmetry group after branching, and solve the convex continuous <u>relaxation</u> on the z. (instead of x-) space

Orbital Shrinking

- Idea: relax "individual integrality" into "surrogate integrality"
- **EXTEND:** Introduce additional z-variables $z_h = \sum_{j \in O_h} x_j$, $h = 1, \dots, k$ along with the integrality requirement z_h integer, $h = 1, \dots, k$
- RELAX: Remove the integrality requirement on x (but not on z) to obtain a "blurred relaxation" → still a convex MI(N)LP with the same symmetry group
- SHRINK: Reformulate <u>exactly</u> the blurred relaxation on the z-space by just replacing
 x_j → z_h/|O_h| for all j ∈ O_h, h = 1, · · · , k

 \rightarrow still a convex MI(N)LP but of smaller size and with **no symmetry left**

 SOLVE: Solve the shrunken MI(N)LP relaxation to get a lower bound → hopefully much easier than solving the original problem [smaller/no symmetry]



A familiar example

- Consider the Asymmetric TSP on a complete digraph... ... and take an instance with **symmetric** arc costs $c_{ij} = c_{ji}$
- Very inefficient because of symmetry → orbital shrinking will automatically detected orbits

$$(x_{12}, x_{21}) (x_{13}, x_{31}) \cdots (x_{ij}, x_{ji}) \cdots$$

- ... and introduce orbital integer variables $z_{\{ij\}} := x_{ij} + x_{ji}$
- 2-node SECs $\rightarrow z_{\{ij\}} = x_{ij} + x_{ji} \le 1 \rightarrow z_{\{ij\}} \in \{0, 1\}$
- In this case, orbital shrinking yields an **exact reformulation**: optimize on the *z*-space (STSP), get an optimal (integer) z^* , and then optimize on the *x*-space with restriction $x_{ij} + x_{ji} = z^*_{\{ij\}}$ to get an optimal x^*

Discussion

- Can we expect to get a tight relaxation in all cases?
- Certainly **NOT** when
 - a single orbit (or just few) exists \rightarrow 100% symmetrical formulations
 - Removing detailed integrality on the single x's oversimplifies the problem \rightarrow trivial relaxation on the z-space
 - e.g. bin packing problem with 2-index (item,bin) x-variables
- Hopefully YES when the blurred relaxation still has a structure that requires nontrivial branching/cuts to be solved
 - rich structure induced by integrality of the *z* var.s only

Illustrative experiments

- Testbed: Margot's website (100% symmetrical instances)
- Working with a subgroup of G generated by a subset of generators
 Tradeoff between size and expected tightness of the shrunken relaxation
- Idea:

1. sort the k (say) generators somehow \rightarrow generators with small cycles first...

2. consider the subgroup of G induced by the first $\,\ell\,$ (say) generators



Typical behaviour

sts81								
ℓ/k	obj	CPU						
1/14	45	3.60						
2/14	45	1.51						
3/14	45	1.18						
4/14	45	1.13						
5/14	33	0.01						
6/14	33	0.01						
7/14	33	0.02						
8/14	33	0.00						
9/14	29	0.02						
10/14	29	0.00						
11/14	29	0.01						
12/14	28	0.01						
13/14	28	0.00						
14/14	27	0.00						



Hand-picked thresholds

Instance	G_ℓ	LP	CPU
ca36243	49	48	0.07
clique9	∞	36	0.06
cod105	-16	-18	4.91
cod105r	-13	-15	0.25
cod83	-26	-28	0.12
cod83r	-22	-25	4.44
cod93	-48	-51	3.07
cod93r	-46	-47	2.74
cov1075	19	18	3.03
cov1076	44	43	185.83
cov954	28	26	0.45
mered	∞	140	0.12
04_35	∞	70	0.07
oa36243	∞	48	0.75
oa77247	∞	112	0.00
of5_14_7	∞	35	0.13
of7_18_9	∞	63	0.04
pa36243	-44	-48	1.26
sts135	60	45	0.05
sts27	12	9	0.01
sts45	24	15	0.39
sts63	27	21	0.00
sts81	33	27	0.00

Automatically-chosen thresholds

Instance	ℓ/k	best	G_1	G_ℓ	CPU	cpx_t	LP
ca36243	3/6	49*	49	48	0.02		48
clique9	5/15	∞^*	∞	∞	0.06	0.17	36
cod105	3/11	-12^*	limit	-14.09^{\dagger}	limit		-18
cod105r	3/10	-11*	-11	-11	24.12	28.36	-15
cod83	3/9	-20*	-21	-24	16.78	9.54	-28
cod83r	3/7	-19*	-21	-22	4.44	7.85	-25
cod93	3/10	-40		-46.11^\dagger	limit		-51
cod93r	3/8	-38	-39	-44	271.74	446.48	-47
cov1075	3/9	20*	20	19	3.03	79.79	18
cov1076	3/9	45	44	43	2.78		43
cov954	3/8	30^{*}	28	26	0.11		26
mered	21/31	∞^*	∞	∞	0.15	3.37	140
04_35	3/9	∞^*	∞	70	0.00		70
oa36243	3/6	∞^*	∞	48	0.01		48
oa77247	3/7	∞^*	∞	∞	0.10	265.92	112
of5_14_7	7/9	∞^*	∞	35	0.00		35
of7_18_9	7/16	∞^*	∞	∞	0.09	0.15	63
pa36243	3/6	-44*	-44	-48	0.01		-48
sts135	3/8	106	75	60	0.11	109.81	45
sts27	4/8	18*	14	12	0.01	1.05	9
sts45	2/5	30*	24	15	0.00		15
sts63	4/9	45^{*}	36	27	0.02	1.99	21
sts81	5/14	61	45	33	0.01	3.92	27

Research questions

- Identify relevant classes of problems suitable to orbital shrinking (i.e., with a rich structure on the z-space left after shrinking)
- Exploit **cuts** taken from the shrunken formulation on the *z* var.s
- Conditions under which the shrunken relaxation is in fact **exact**
- Full **integration** of orbital shrinking within an exact solution scheme
- Use as a **heuristic**: find an optimal *z*, fix it, and optimize on *x* ...